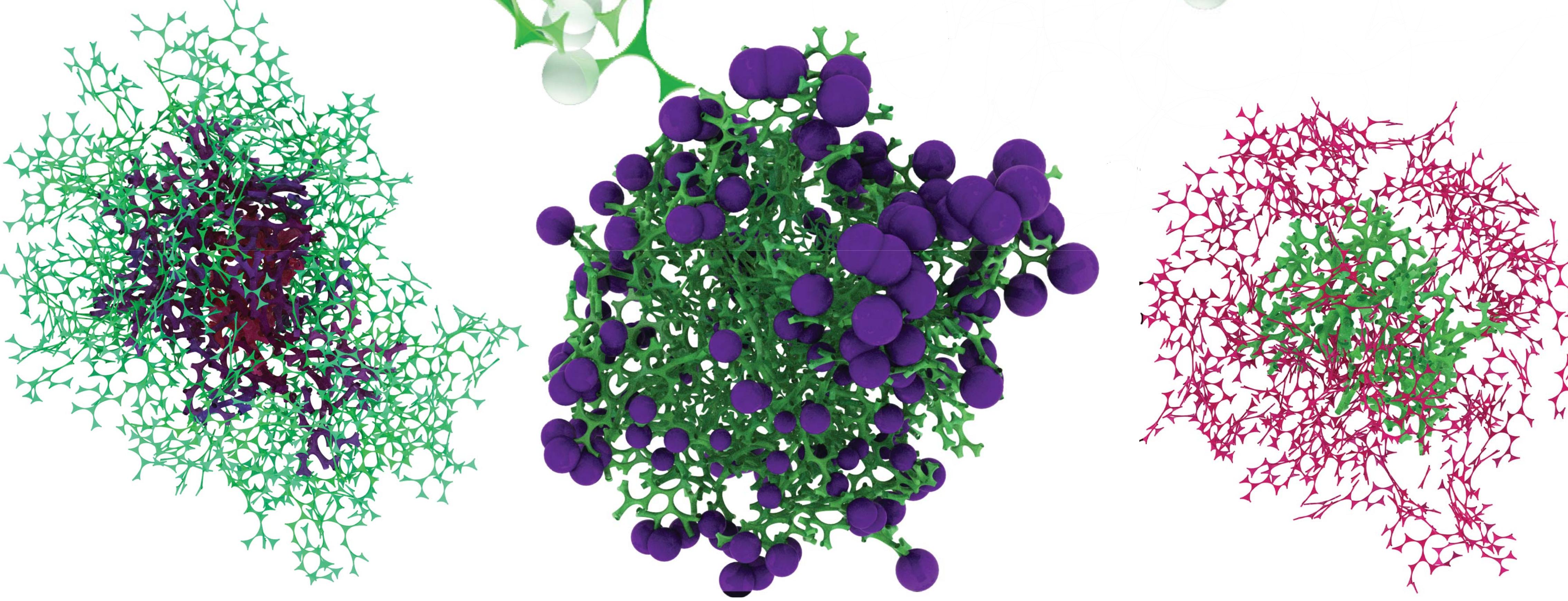


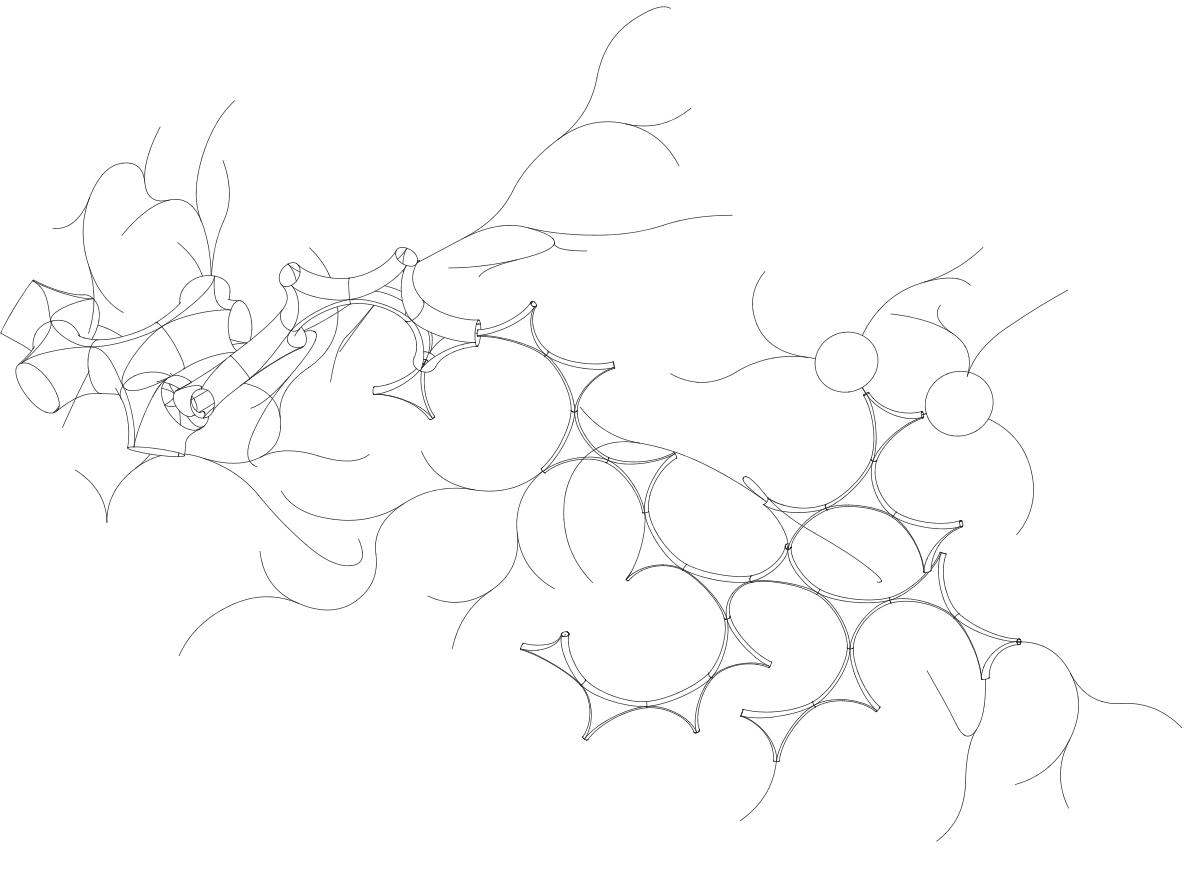
# VS CODING FORM

OMAR G. MUÑOZ

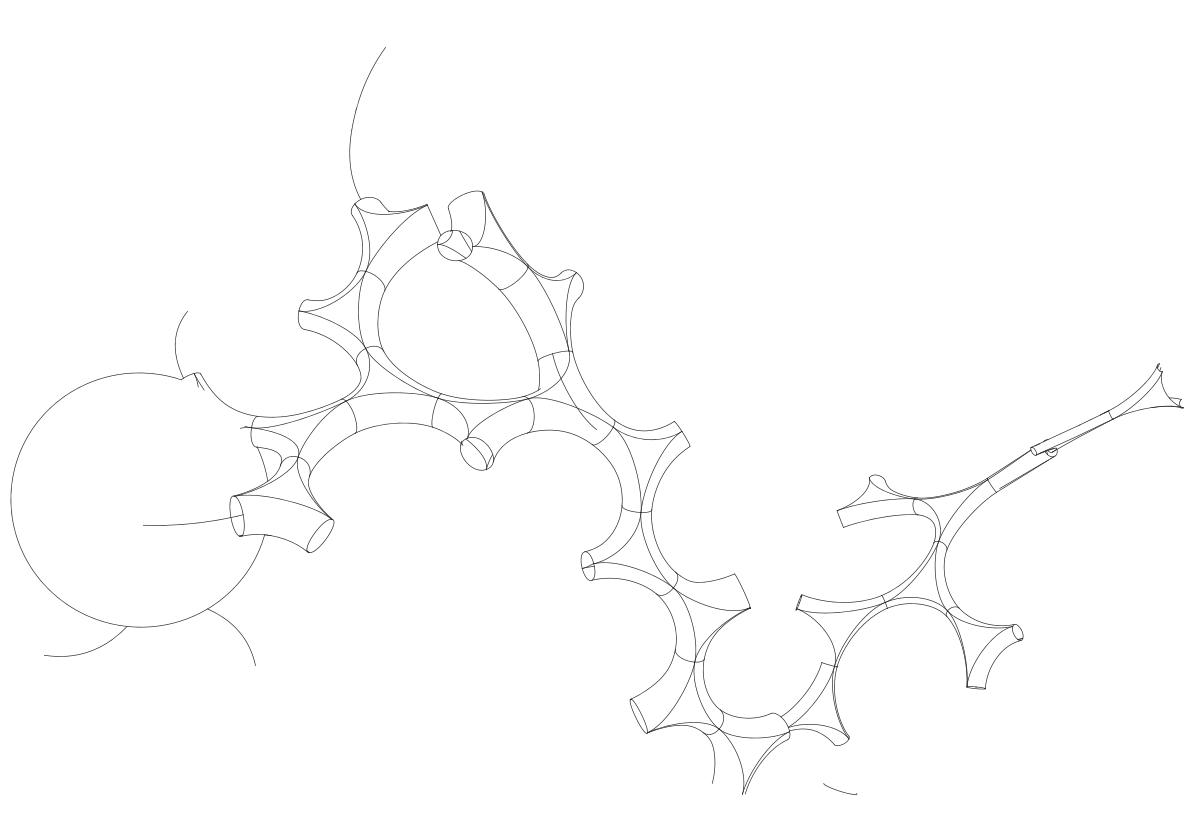
TIME VARIABLE



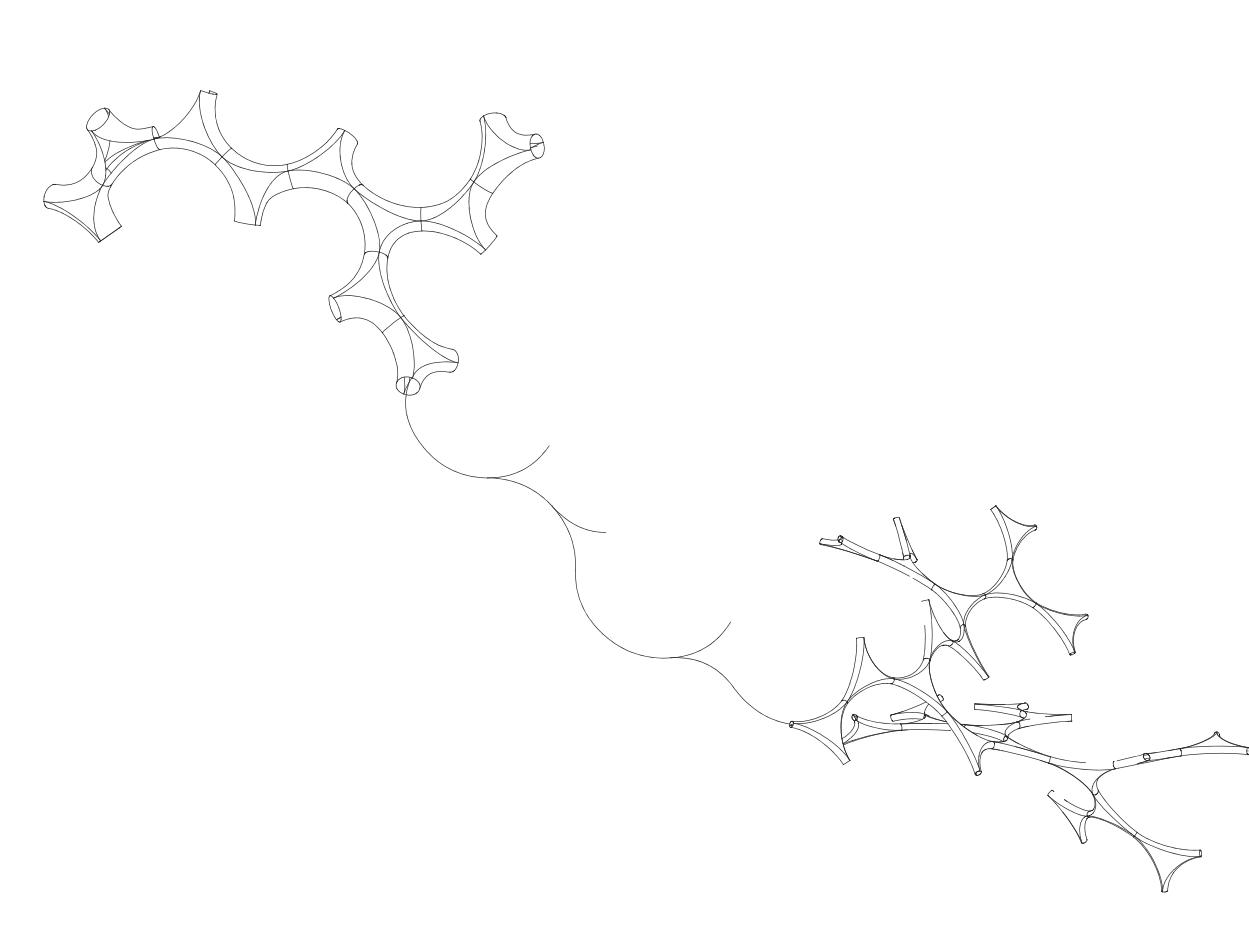
OUTPUT 1



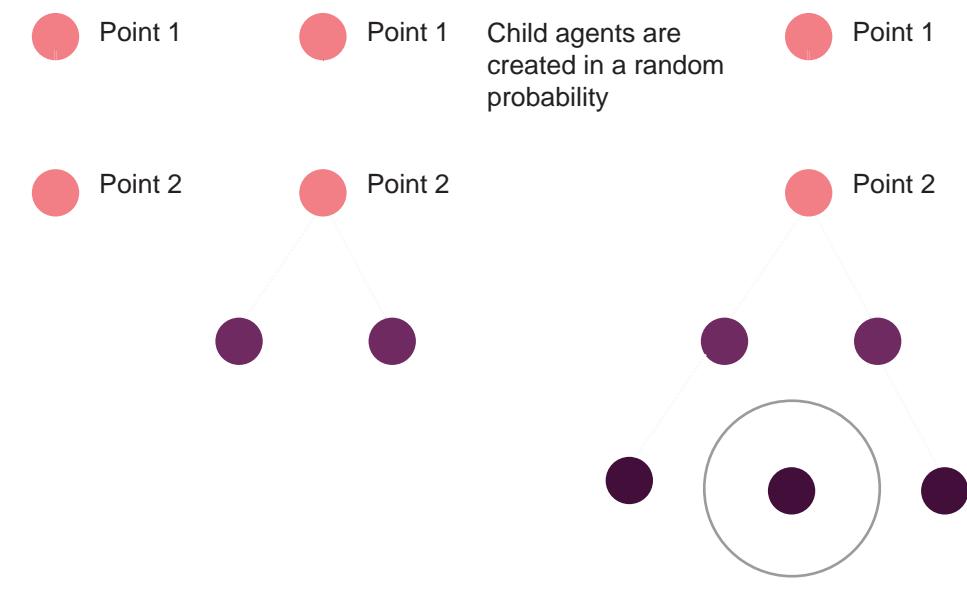
OUTPUT 2



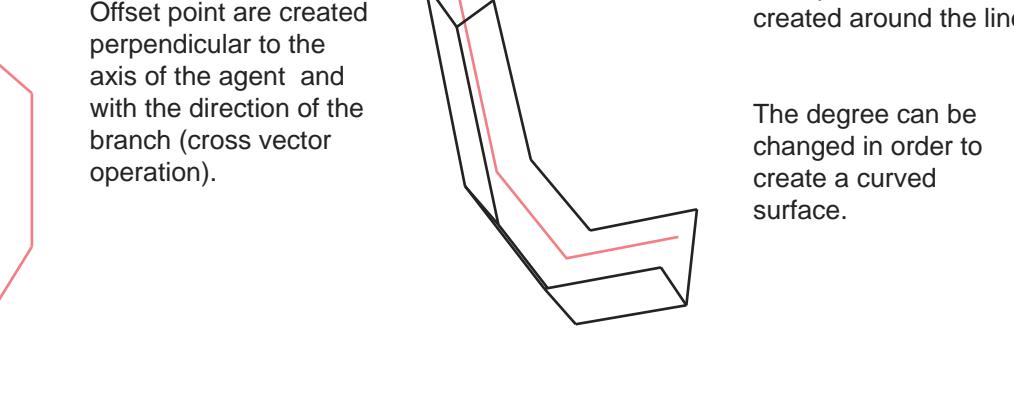
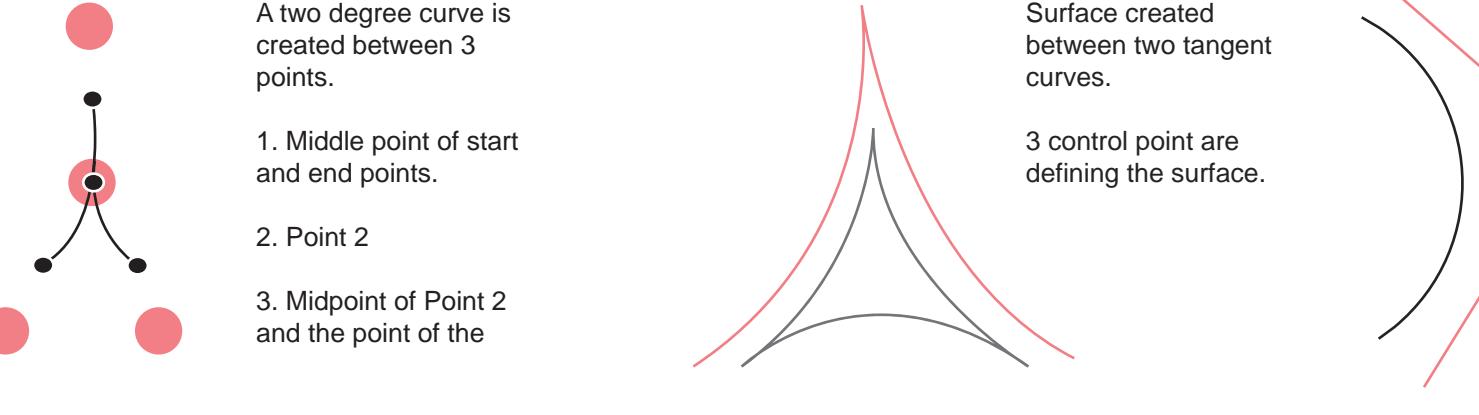
OUTPUT 3



## AGENT ALGORITHM DIAGRAM LINE AGENT



## AGENT GEOMETRY DIAGRAM SURFACE AROUND LINEAGENT



```
import processing.opengl.*;
import peasy.*;

void setup(){
    size(980, 860, IG.GL);
    IRand.init(3);
    IG.duration(33);
    //second and third vector needs to be perpendicular
    new LineAgent(new IVec(0,0), new IVec(1,0),
    new IVec(0,0,1)).clr(1,0,0.5);
    IG.fill();
}

static class LineAgent extends Agent{
    static ILayer layer1 = IG.layer("Layer1");
    static ILayer layer2 = IG.layer("Layer2");
    static ILayer layer3 = IG.layer("Layer3");
    static ILayer layer4 = IG.layer("Layer4");
    static ILayer layer5 = IG.layer("Layer5");
    static ILayer layer6 = IG.layer("Layer6");
    static ILayer layer7 = IG.layer("Layer7");
    static ILayer layer8 = IG.layer("Layer8");
    static double length = 2;
    static double clearance = 1.99; //less than length
    IVec p1, p2, axis;
    boolean isColliding=false;
    LineAgent(IF vec pt, IVec dir, IVec ax){
        p1 = pt;
        p2 = pt.dup().add(dir.dup().len(length));
        axis = ax;
    }
}
```

```
void interact(ArrayList<IDynamics> agents){
    super.interact(agents);
    if(time > 0.001){ //for the first time
        for(i=0; i< agents.size() && !isColliding; i++){
            if(agents.get(i) instanceof LineAgent){
                LineAgent.lineAgent =
                    (LineAgent)agents.get(i);
                if(!lineAgent.isThis() && agents.include("this")){
                    //clearing check of end point
                    if(lineAgent.pt2.dist(pt2) < clearance){
                        isColliding=true;
                    }
                }
            }
        }
    }
}

static class LineAgent extends Agent{
    static ILayer layer1 = IG.layer("Layer1");
    static ILayer layer2 = IG.layer("Layer2");
    static ILayer layer3 = IG.layer("Layer3");
    static ILayer layer4 = IG.layer("Layer4");
    static ILayer layer5 = IG.layer("Layer5");
    static ILayer layer6 = IG.layer("Layer6");
    static ILayer layer7 = IG.layer("Layer7");
    static ILayer layer8 = IG.layer("Layer8");
    void update(){
        super.update();
        if(isColliding){
            del();
        }
    }
}

double offsetWidth = 0;
double depth = 0;

if((IG.time)>15){
    offsetWidth = -8;
    depth = .8;
}
else if((IG.time)>20){
    offsetWidth = -4;
    depth = .4;
}
else if((IG.time)>30){
    offsetWidth = -1;
    depth = .1;
}
```

```
IVec nextDir2 = dir.dup().rot(axis,-IRand.getPI(4,PI/3));
    }

if((G.time)==15){ clr(0,0,0,0.5); }
else if((G.time)==25){ clr(0,5,1,0.5); }
else if((G.time)==30){ clr(5,1,5,0); }

IVec mid1 = pt1.mid(pt2);
IVec mid2 = pt2.mid(nextPt1);
IVec mid3 = pt1.mid(nextPt2);
//mid of midpoints
IVec quarter1 = p2.mid(mid1);
IVec quarter2 = p2.mid(mid2);
IVec quarter3 = p2.mid(mid3);

IVec depthV1 = dir.cross(axis).len(offsetWidth);
IVec depthV2 = nextDir1.cross(nextAxis1).len(offsetWidth);
IVec depthV3 = nextDir2.cross(nextAxis2).len(offsetWidth);

if(depth > 0){
    createEdgeSurface(mid1,quarter1,quarter2,mid2,
    offsetDir1,offsetDir2,
    depthV1,depthV2,clr(r,g,b));
    createEdgeSurface(mid2,quarter2,quarter3,mid3,
    offsetDir2.dup().flip(),offset3,
    depthV2,depthV3,clr(r,g,b));
    createEdgeSurface(mid3,quarter3,quarter1,mid1,
    offset3.dup().flip(),offset1.dup().flip(),
    depthV3,depthV1,clr(r,g,b));
}

createCapSurface(mid1.quarter1,mid2.quarter2,mid3.quarter3,
    depthV1.dup().depthVec2.depthVec3,clr(clr)).layer(layer4);
createCapSurface(mid1.quarter1,mid3.quarter3,mid2.quarter2,
    depthVec1.flip(),depthVec3.flip(),depthVec2.flip()).clr(clr)
    .layer(layer5);
new LineAgent(pt2, nextDir2, nextAxis2).clr(g,b);
anyChild=true;
```

```
//child agents color
int r = clr().getRed() + IRand.getInt(-10,10);
int g = clr().getGreen() + IRand.getInt(10,8);
int b = clr().getBlue() + IRand.getInt(10,8);

boolean anyChild=false;
if(IRand.percent(100)){ //bend
    dir.dup().rot(axis,IRand.getPI(3/12));
    //degree 2 curve at midpoint of pt1&pt2, pt2,
    //and midpoint of pt2 and next agent's point
    new ICurve(new IVec[] { pt1.mid(pt2),
    pt2, pt2.mid(pt2.cp(nextDir1)), 2).clr(1).layer(layer6);
}

if(IRand.percent(50)){ //bend the other way
    dir.dup().rot(axis,-IRand.getPI(3/12));
    new ICurve(new IVec[] { pt1.mid(pt2),
    pt2, pt2.mid(pt2.cp(nextDir1)), 2).clr(1).layer(layer6);
}

if((anyChild || IG.time())==30){
    double dist = pt2.dist(new IVec(0,0,0));
    double radius = dist*0.03;
    new ISphere(pt2,radius).clr(1).layer(layer8);
}
```

return new ISurface(cpts, 3, 3);

ISurface createCapSurface(IVec pt1, IVec pt2,

IVec pt3, Vec pt4,

IVec pt5, Vec pt6,

IVec shiftDir1,

IVec shiftDir2,

IVec shiftDir3)

IVec[] cpts = new IVec[4];

cpts[0] = pt1.dup().add(shiftDir1);

cpts[1] = pt1.dup().add(shiftDir2);

cpts[2] = pt2.dup().add(shiftDir1);

cpts[3] = pt2.dup().add(shiftDir2);

IVec extrudeDir1,

IVec extrudeDir2,

IVec[] cpt = new IVec[4];

cpt[0] = pt1.dup().add(extrudeDir1);

cpt[1] = pt2.dup().add(extrudeDir1);

cpt[2] = pt1.dup().add(extrudeDir2);

cpt[3] = pt2.dup().add(extrudeDir2);

IVec offsetDir1,

IVec offsetDir2,

IVec offsetDir3,

IVec offsetDir4,

IVec offsetDir5,

IVec offsetDir6,

IVec offsetDir7,

IVec offsetDir8,

IVec offsetDir9,

IVec offsetDir10,

IVec offsetDir11,

IVec offsetDir12,

IVec offsetDir13,

IVec offsetDir14,

IVec offsetDir15,

IVec offsetDir16,

IVec offsetDir17,

IVec offsetDir18,

IVec offsetDir19,

IVec offsetDir20,

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IVec offsetDir109,

IVec offsetDir110,