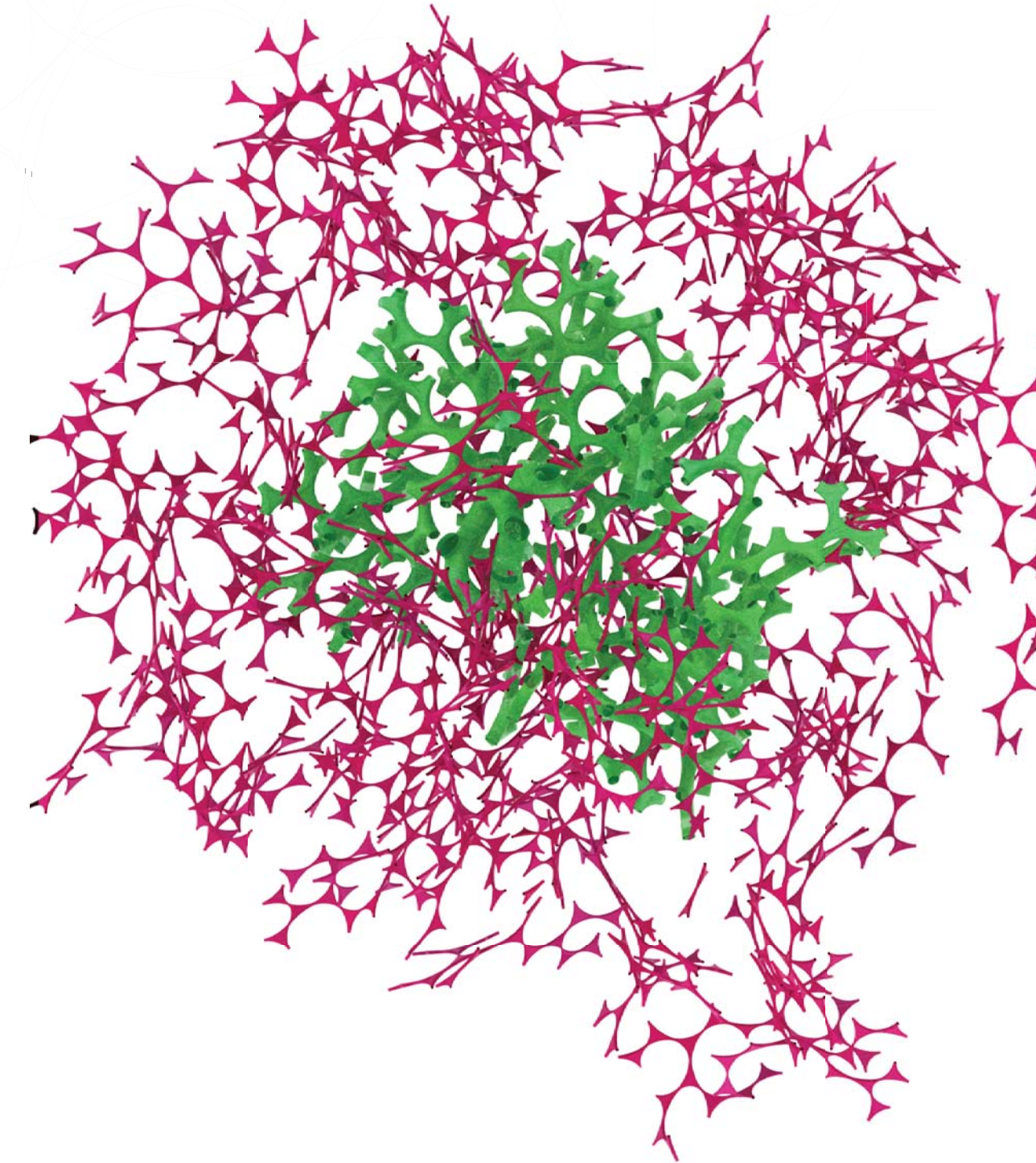
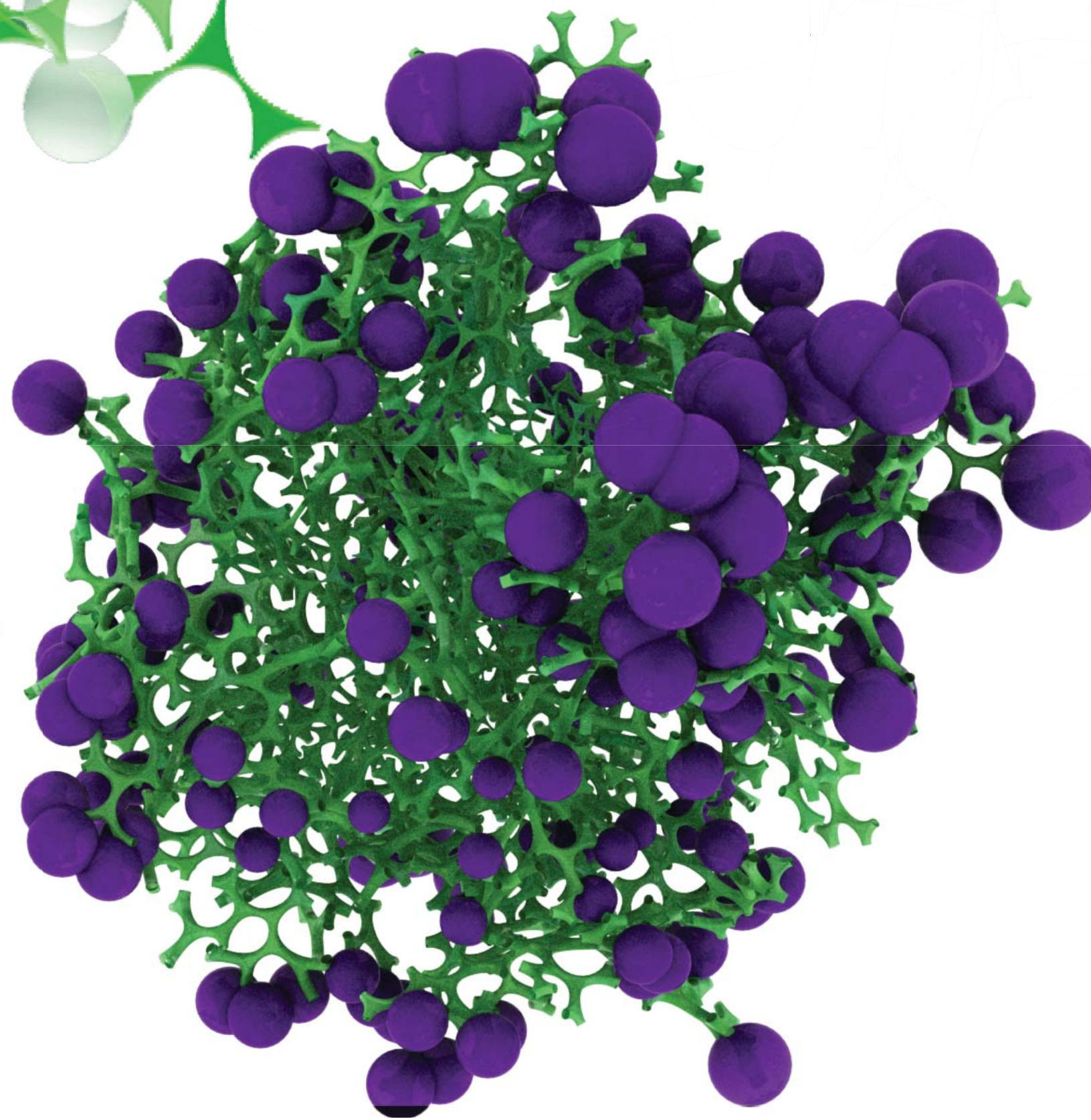
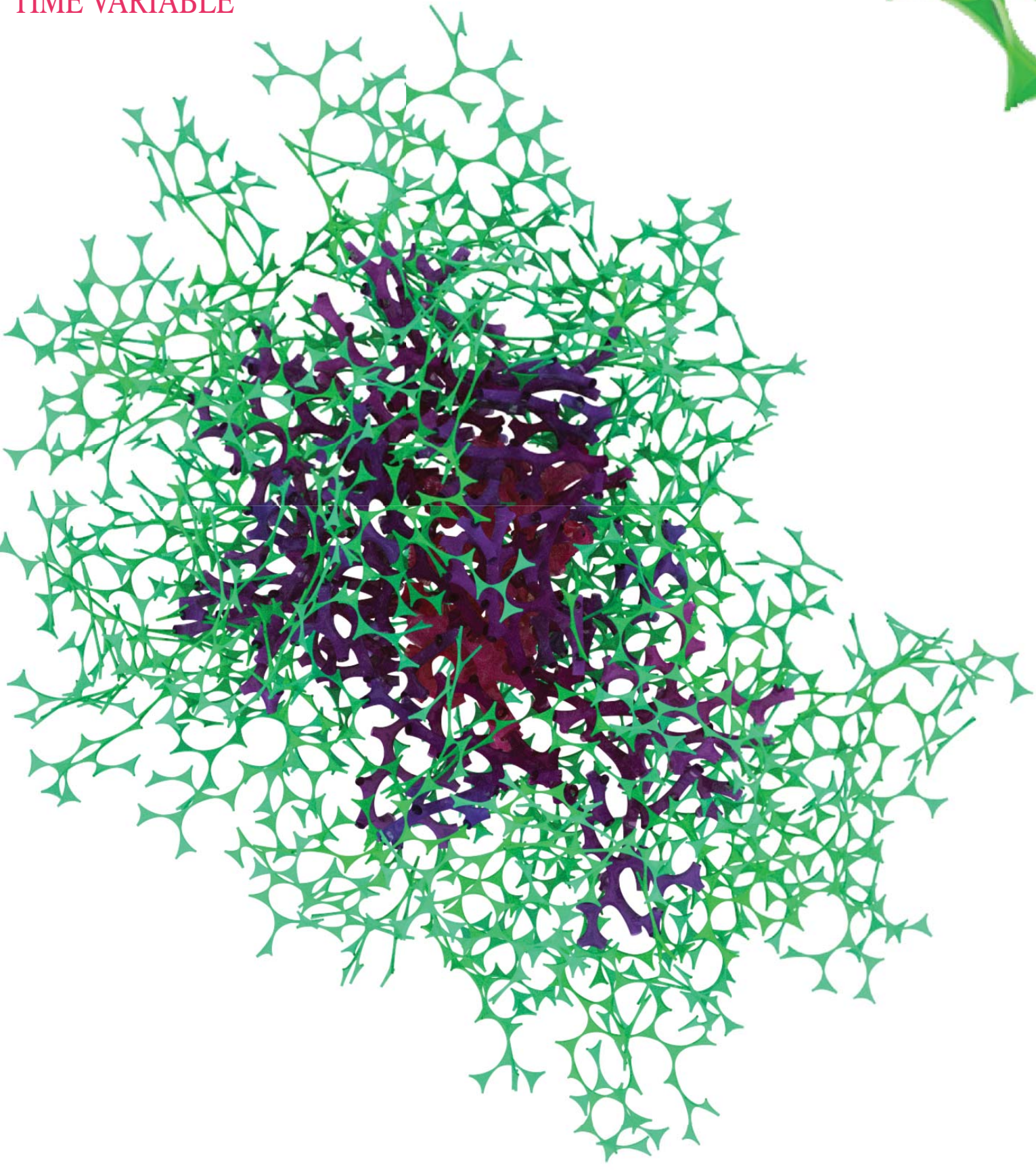


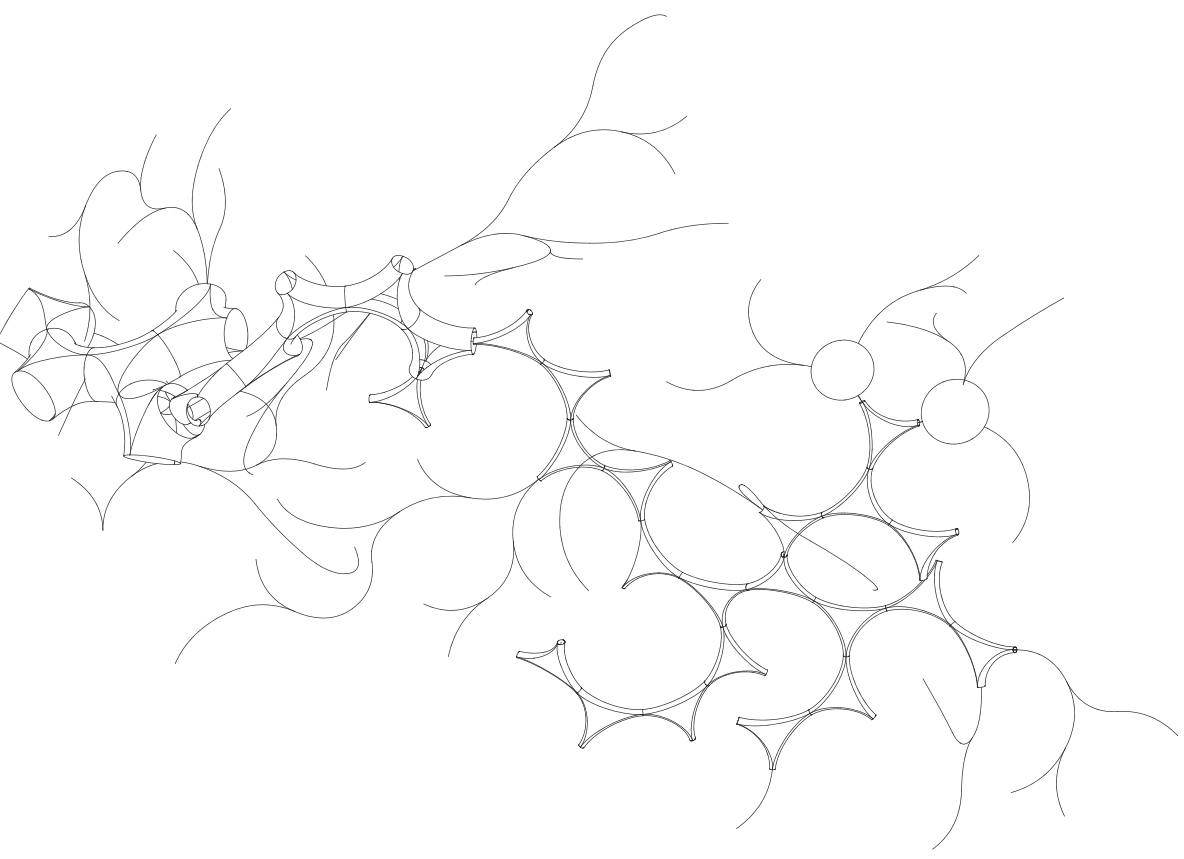
VS CODING FORM

OMAR G. MUNOZ

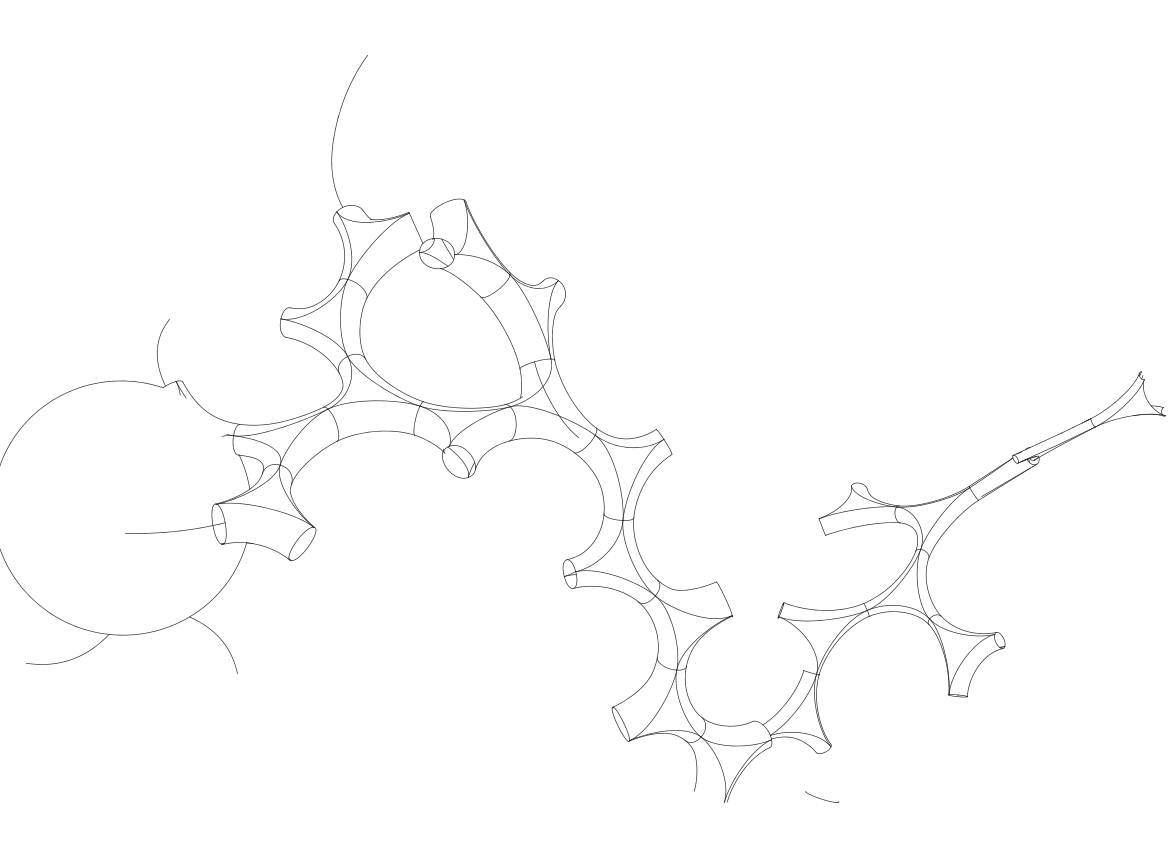
TIME VARIABLE



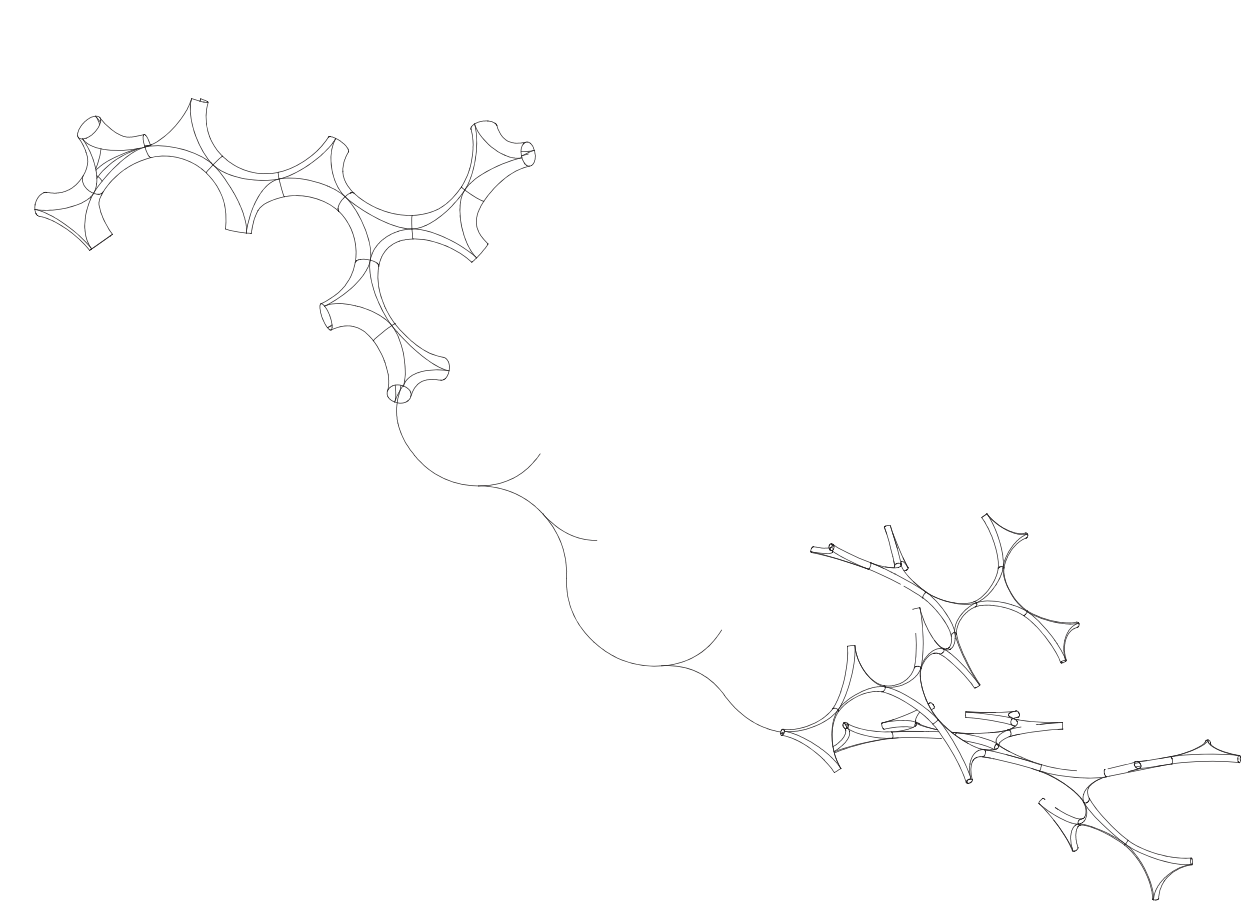
OUTPUT 1



OUTPUT 2

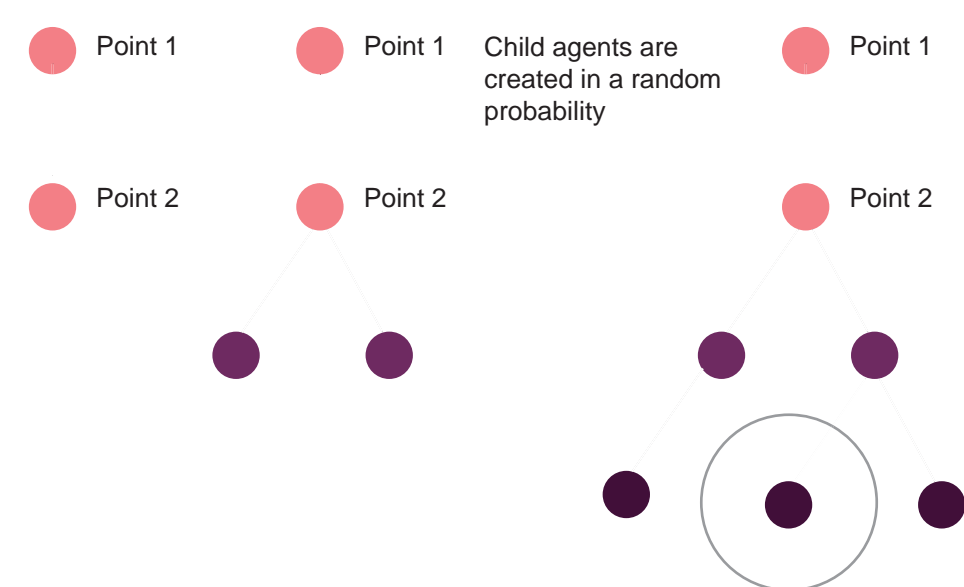


OUTPUT 3



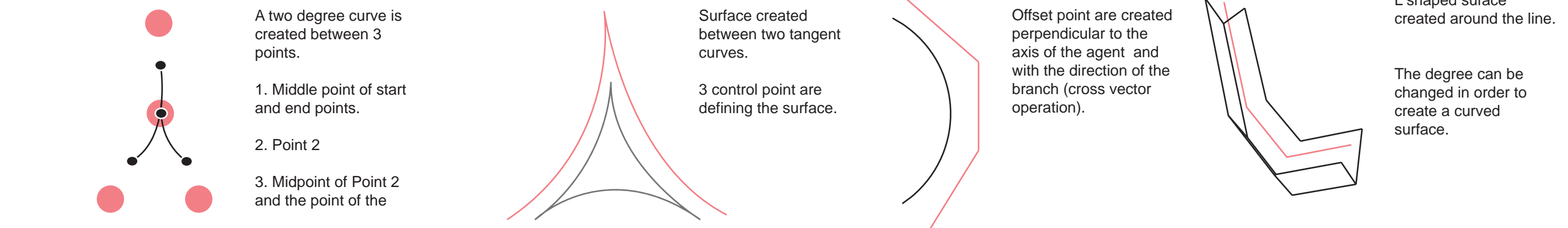
AGENT ALGORITHM DIAGRAM

LINE AGENT



AGENT GEOMETRY DIAGRAM

SURFACE AROUND LINEAGENT



```
import processing.opengl.*;
import Igo.*;

void setup(){
  size(980, 860, IGO.GL);
  IIRand.init(33);
  IGO.duration(33);
  //second and third vector needs to be perpendicular
  new IVec(0.0,0.0), new IVec(1.0,0.0),
  new IVec(0.0,1.0).clr(1.0,0.0,0.5);
  IGO.fill();
}

static class LineAgent extends IAgent{
  static ILayer layer1 = IGO.layer("Layer1");
  static ILayer layer2 = IGO.layer("Layer2");
  static ILayer layer3 = IGO.layer("Layer3");
  static ILayer layer4 = IGO.layer("Layer4");
  static ILayer layer5 = IGO.layer("Layer5");
  static ILayer layer6 = IGO.layer("Layer6");
  static ILayer layer7 = IGO.layer("Layer7");
  static ILayer layer8 = IGO.layer("Layer8");

  static double length = 2;
  static double clearance = 1.99; //less than length
  IVec pt1, pt2, axis;
  boolean isColliding=false;

  LineAgent(IVec pt, IVec dir, IVec ax){
    pt1 = pt;
    pt2 = pt.dup().add(dir.dup()).len(length);
    axis = ax;
  }

  void interact(ArrayList< IDynamics > agents){
    super.interact(agents);
    if(time == 0){ //only in the first time
      for(int i=0; i < agents.size() && !isColliding; i++){
        IAgent agent = agents.get(i);
        LineAgent lineAgent = (LineAgent)agent;
        if(lineAgent != this){ //agents include "this"
          //checking clearance of end point
          if(lineAgent.pt2.dist(pt2) < clearance){
            isColliding=true;
          }
        }
      }
    }
    void update(){
      super.update();
      if(isColliding){
        del();
      }
    }
    //new ICurve(pt1,pt2); // center line
    IVec dir = pt2.diff(pt1);
    // child dir & points
    IVec nextDir1 = dir.dup().rot(axis, IIRand.get(PI/4,PI/3));
    IVec nextDir2 = dir.dup().rot(axis, -IIRand.get(PI/4,PI/3));
    IVec nextPt1 = pt2.cp(nextDir1);
    IVec nextPt2 = pt2.cp(nextDir2);
    //midpoints
    IVec mid1 = pt1.mid(pt2);
    IVec mid2 = pt2.mid(nextPt1);
    IVec mid3 = pt2.mid(nextPt2);
    //mid of midpoints
    IVec quarter1 = pt1.mid(mid1);
    IVec quarter2 = pt2.mid(mid2);
    IVec quarter3 = pt2.mid(mid3);
    //axis of child agents
    IVec nextAxis1 = axis.dup().rot(nextDir1, IIRand.get(-PI/4,PI/4));
    IVec nextAxis2 = axis.dup().rot(nextDir2, IIRand.get(-PI/4,PI/4));
    double offsetWidth = 0;
    double depth = 0;
    if((IG.time()-15){
      offsetWidth = -.8;
      depth = .8;
    }
    else if((IG.time()-20){
      offsetWidth = -.4;
      depth = .4;
    }
    else if((IG.time()-30){
      offsetWidth = -.1;
      depth = .1;
    }
    }

    //child agents color
    int r = clr().getRed() + IIRand.get(10,10);
    int g = clr().getGreen()+ IIRand.get(10,8);
    int b = clr().getBlue()+ IIRand.get(10,8);
    boolean anyChild=false;
    if((IIRand.percent(100))){ //bend
      dir.dup().rot(axis, IIRand.get(PI/3,PI/3*2));
      //degree 2 curve at midpoint of pt1&pt2, pt2,
      //and midpoint of pt2 and next agent's point
      new ICurve(new IVec[] { pt1.mid(pt2),
        pt2,
        pt2.mid(pt2.cp(nextDir1)) },
        2).clr(1.).layer(layer6);
      new LineAgent(pt2, nextDir1, nextAxis1).clr(r,g,b);
      anyChild=true;
    }
    if((IIRand.percent(50))){ //bend the other way
      dir.dup().rot(axis, -IIRand.get(PI/3,PI/3*2));
      new ICurve(new IVec[] { pt1.mid(pt2),
        pt2,
        pt2.mid(pt2.cp(nextDir2)) },
        2).clr(1.).layer(layer7);
      new LineAgent(pt2, nextDir2, nextAxis2).clr(r,g,b);
      anyChild=true;
    }
    if(!anyChild || (IG.time()-30){
      double dist = pt2.dist(new IVec(0.0,0.0));
      double radius = dist*0.03;
      new ISphere(pt2,radius).clr(1.).layer(layer8);
      ISurface createCapSurface(IVec pt1, IVec pt2,
        IVec pt3, IVec pt4,
        IVec pt5, IVec pt6,
        IVec shiftDir1,
        IVec shiftDir2,
        IVec shiftDir3){
        IVec[] cps = new IVec[4];
        cps[0][0] = pt1.dup().add(shiftDir1);
        cps[1][0] = pt1.dup().add(shiftDir2);
        cps[2][0] = pt1.dup().add(shiftDir3);
        cps[3][0] = pt1.dup().add(shiftDir1);
        cps[0][1] = pt2.dup().add(shiftDir1);
        cps[1][1] = pt2.dup().add(shiftDir2);
        cps[2][1] = pt2.dup().add(shiftDir3);
        cps[3][1] = pt2.dup().add(shiftDir1);
        cps[0][2] = pt4.dup().add(shiftDir2);
        cps[1][2] = pt4.dup().add(shiftDir3);
        cps[2][2] = pt4.mid(pt6).add(shiftDir2.mid(shiftDir3));
        cps[3][2] = pt6.dup().add(shiftDir2);
        cps[0][3] = pt3.dup().add(shiftDir2);
        cps[1][3] = pt3.dup().add(shiftDir3);
        cps[2][3] = pt6.dup().add(shiftDir3);
        cps[3][3] = pt5.dup().add(shiftDir3);
        return new ISurface(cps, 3, 3);
      }
    }
  }
}
```